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الأسبوع

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محاضرة 6

Ex: $\overline{GH}(z) = \frac{K(z-0.2)}{(z-1)(z+0.6)^2}$, Draw the root locus and find the range of k for stability

1 Poles: $n_p = 3 \Rightarrow 1, -0.6, -0.6$
Zeros: $n_z = 1 \Rightarrow 0.2$

2 z -plane

3 real part: $1 \rightarrow 0.2$

4 Asymptotes

1- no. of asy = $n_p - n_z$

2- $\sigma_c = \frac{\sum \text{Poles} - \sum \text{Zeros}}{n_p - n_z} = -0.2$

3- $\theta = \frac{(2L+1)\pi}{n_p - n_z} \Rightarrow L=0, \theta_1 \Rightarrow 90^\circ$
 $L=1, \theta_2 \Rightarrow -90^\circ$

5 Determine K_{cr}

$$1) K_{cr} = \frac{L_1 L_{2,3}}{L_3} = \checkmark$$

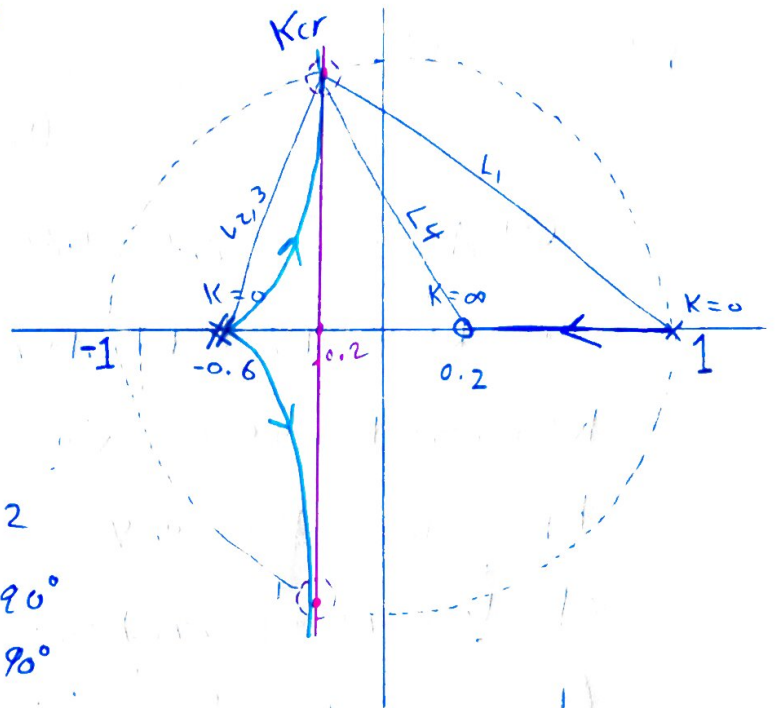
2 using Bilinear Transformation

$$\text{ch. eqn} \Rightarrow 1 + \frac{K(z-0.2)}{(z-1)(z+0.6)^2} = 0$$

$$(z-1)(z+0.6)^2 + K(z-0.2) = 0$$

$$(0.32 + 1.2K)r^3 + (2.56 - 1.6K)r^2 + (5.12 - 0.4K)r + 0.8K$$

\Rightarrow continue



$$\begin{array}{l|l}
 r^3 & 0.32 + 1.2K \quad (1) \quad 5.12 - 0.4K \\
 r^2 & 2.56 - 1.6K \quad (2) \quad 0.8K \\
 r^1 & A \quad (3) \\
 r^0 & 0.8K \quad (4)
 \end{array}$$

$(1) \quad 0.32 + 1.2K > 0$
 $\Rightarrow K > -0.267$
 $(2) \quad 2.56 - 1.6K > 0$
 $\Rightarrow K < 1.6$
 $(4) \quad 0.8K > 0 \Rightarrow K > 0$

$$(3) \quad A > 0 \Rightarrow (2.56 - 1.6K)(5.12 - 0.4K) - 0.8K(0.32 + 1.2K) > 0$$

$$-0.32K^2 - 9.472K + 13.167 > 0$$

$$K^2 + 29.6K - 40.96 < 0$$

$$K_{1,2} = 1.32 \text{ \& } -30.92$$

$$(K - 1.32)(K + 30.92) < 0$$

$$K > 1.32 \text{ \& } K < -30.92 \quad \times$$

$$K < 1.32 \text{ \& } K > -30.92 \quad \checkmark$$

$$\therefore 0 < K < 1.32 \quad K_{cr} = 1.32$$

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* Bode Diagram

To study system properties in freq. domain for a discrete time system, we use bilinear Transformation, to get the system in cont. time domain.

Bilinear Transformation $\boxed{z = \frac{1+r}{1-r}}$

- Remember that it's a relative stability method given open loop Digital T.F. $\overline{GH}(z)$, to Draw the bode Diagram:

① Map from z-domain to r-domain

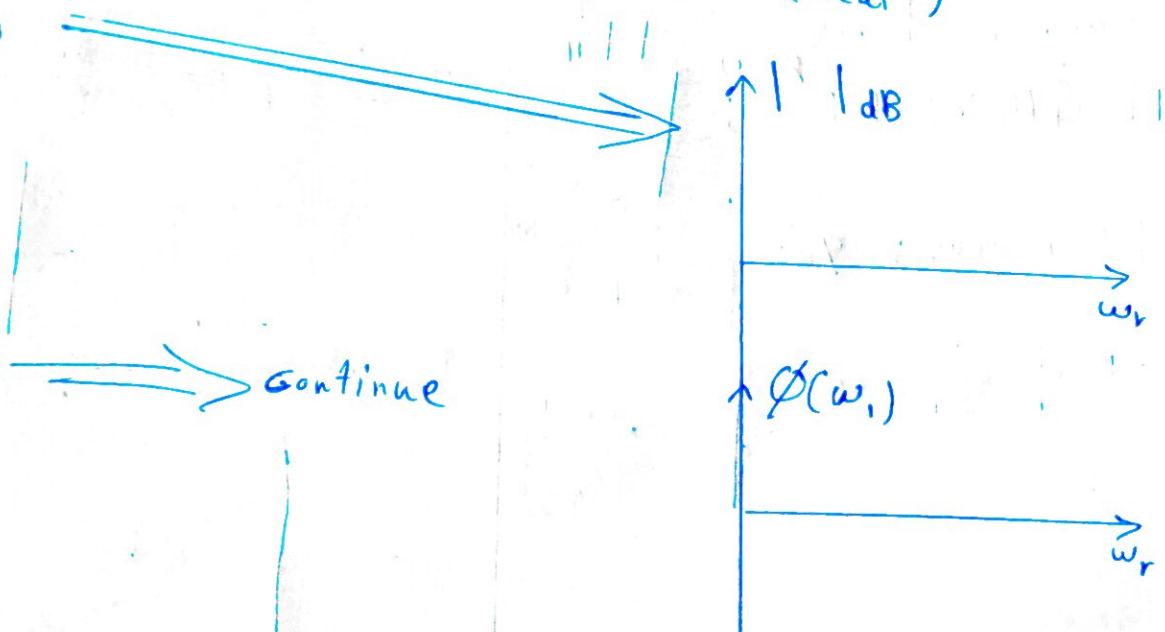
② $\overline{GH}(z) \rightarrow GH(r)$
 $r \rightarrow j\omega_r$

③ $|GH(j\omega_r)| = \frac{|1 - z^{-1}|}{|1 - r^{-1}|}$

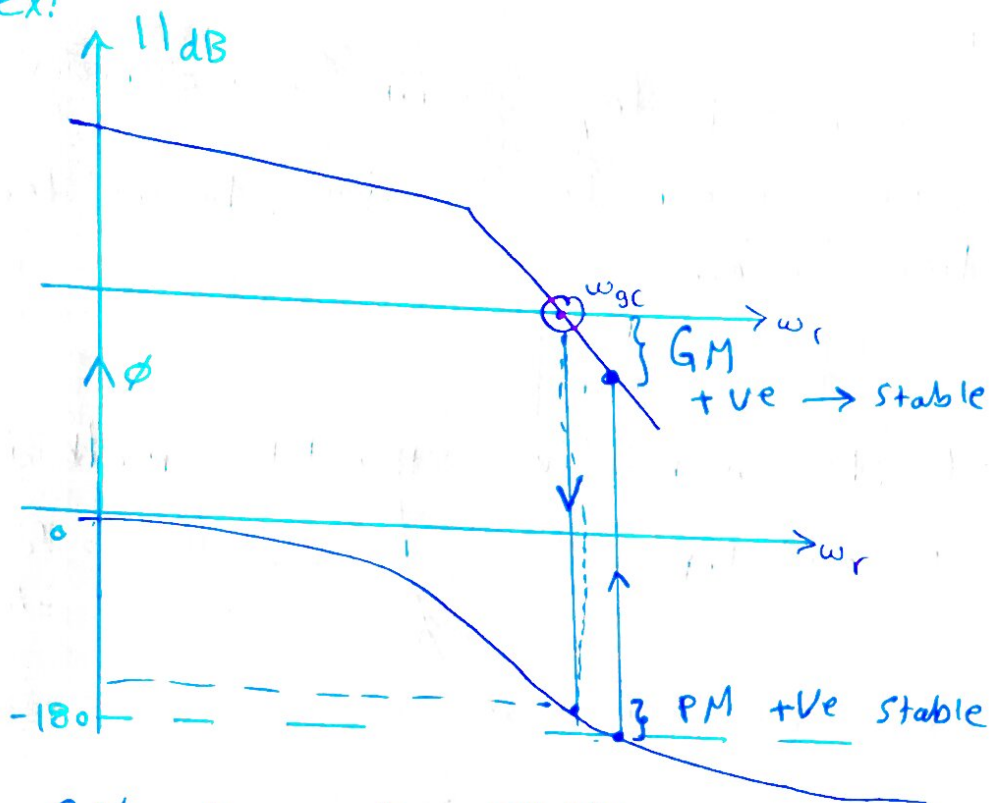
$|GH(j\omega_r)|_{dB} = 20 \log |GH(j\omega_r)|$

④ $\phi(\omega_r) = \angle \frac{1 - z^{-1}}{1 - r^{-1}} ; \tan^{-1} \left(\frac{\text{imag}}{\text{real}} \right)$

⑤ Draw



ex:



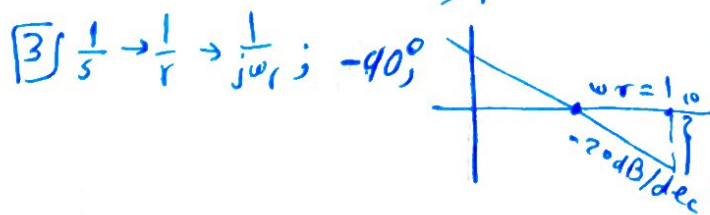
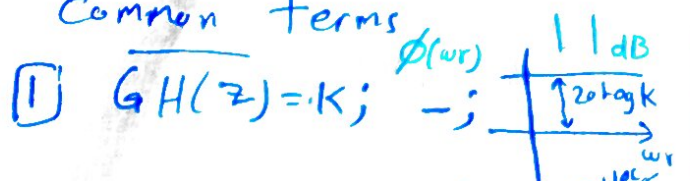
$GM_{dB} > 0 \Rightarrow$ stable

$GM_{dB} < 0 \Rightarrow$ unstable

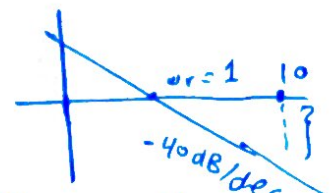
$GM_{dB} = 0 \Rightarrow$ critically stable

Same goes for PM

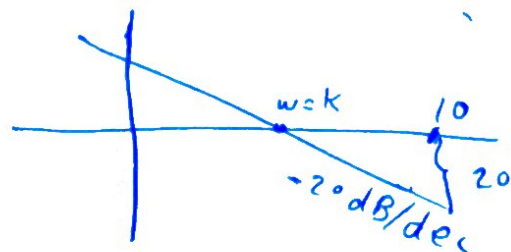
Common terms



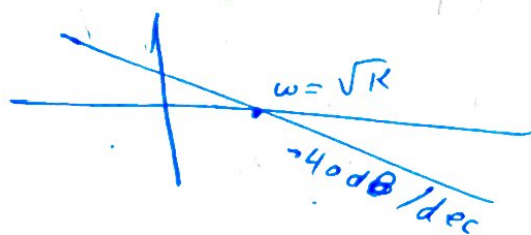
[4] $\frac{1}{s^2} \rightarrow \frac{1}{r^2} \rightarrow \frac{1}{j\omega} \cdot \frac{1}{j\omega}; -180^\circ$



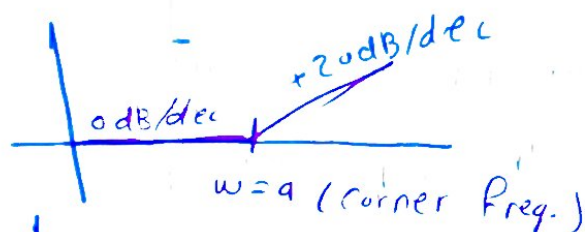
[5] $GH(z) = \frac{1}{s} \rightarrow \frac{K}{r} \rightarrow \frac{K}{j\omega_r}; -90^\circ$



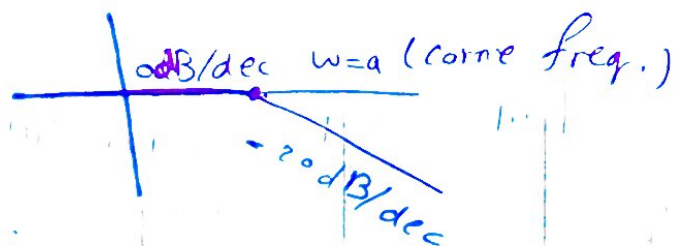
6 $\frac{K}{s^2} \rightarrow \frac{K}{r^2} \rightarrow \frac{K}{j\omega \cdot j\omega} ; -180^\circ$



7 $\bar{G}H(z) = 1 + \frac{s}{a} \xrightarrow{\text{فرع}} 1 + \frac{r}{a} \rightarrow (1 + j\frac{\omega r}{a}) ; \tan^{-1}(\frac{\omega r}{a})$



8 $G_H(z) = \frac{1}{(1 + \frac{s}{a})} \xrightarrow{\text{فرع}} \frac{1}{(1 + j\frac{\omega r}{a})} ; -\tan^{-1} \frac{\omega r}{a}$



Example 1:

Draw the Bode diagram for the following system

$$\bar{G}H(z) = \frac{0.5(z + 0.76)}{(z - 1)(z - 0.45)}$$

and find ω_{gc} & ω_{pc} & GM & PM

① put $z = \frac{1+r}{1-r}$

$$G_H(r) = \frac{0.5 \left(\frac{1+r}{1-r} + 0.76 \right)}{\left(\frac{1+r}{1-r} - 1 \right) \left(\frac{1+r}{1-r} - 0.45 \right)} = \frac{0.5(1-r)(1+r+0.76(1-r))}{(1+r-(1-r))(1+r-0.45(1-r))}$$

$$GH(r) = \frac{0.5(1-r)(1.76 + 0.24r)}{2r(0.55 + 1.45r)}$$

$$GH(r) = \frac{0.8 (0.5)(1.76)(1-r)(1 + \frac{0.24r}{1.76})}{2(0.5)r(1 + \frac{1.45r}{0.55})}$$

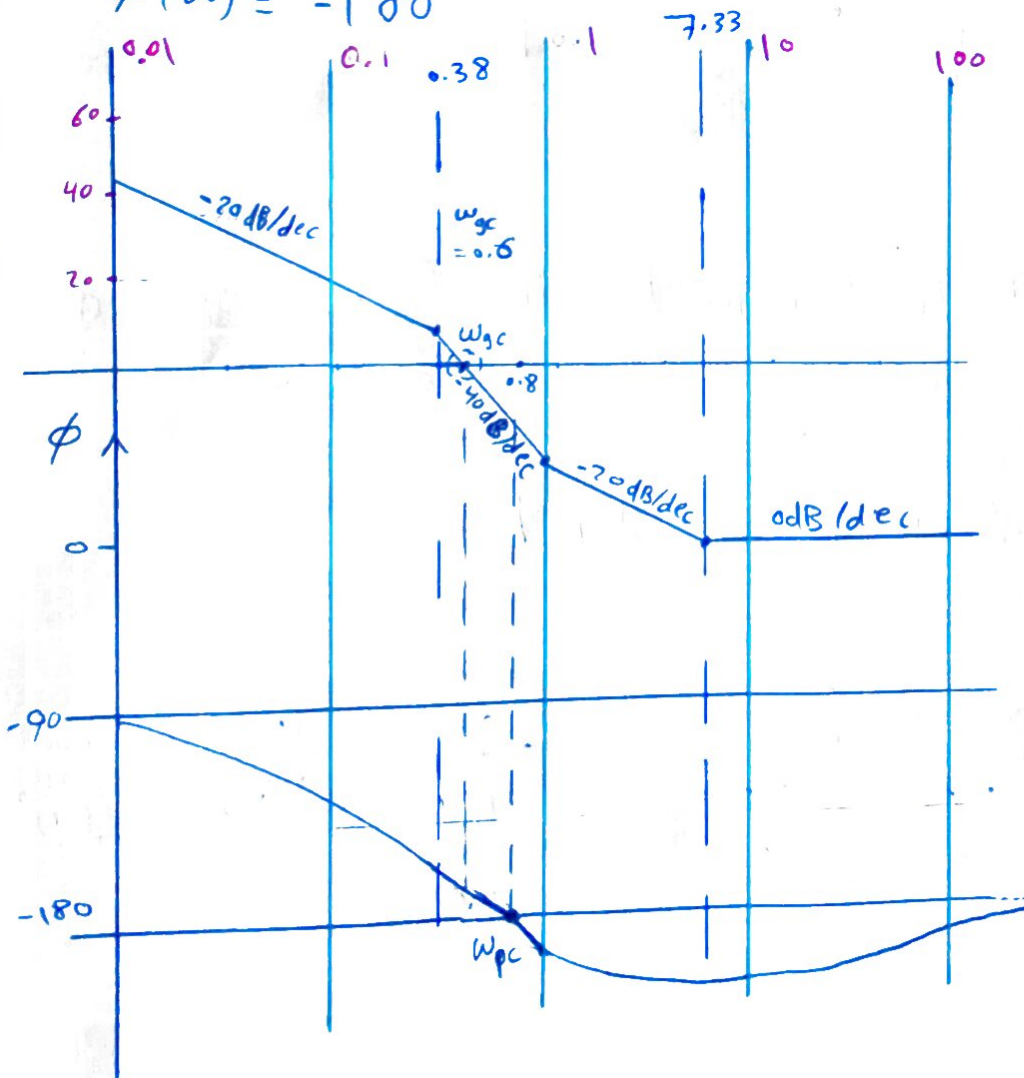
$$= \frac{0.8(1-r)(1 + \frac{r}{7.33})}{r(1 + \frac{r}{0.38})}$$

$$GH(j\omega r) = \frac{0.8(1-j\omega r)(1 + \frac{j\omega r}{7.33})}{j\omega r(1 + \frac{j\omega r}{0.38})}$$

$$\phi(\omega r) = -90 + \underbrace{\tan^{-1}(\omega r)}_{\text{zero}} + \underbrace{\tan^{-1}(\frac{\omega r}{7.33})}_{\text{pole}} - \underbrace{\tan^{-1}(\frac{\omega r}{0.38})}_{\text{pole}}$$

$$\phi(0) = -90$$

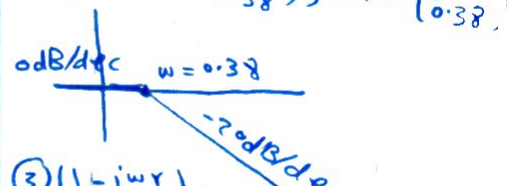
$$\phi(\infty) = -180$$



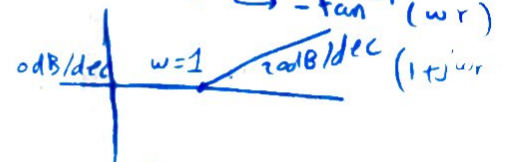
① $\frac{0.8}{j\omega r}$; -90



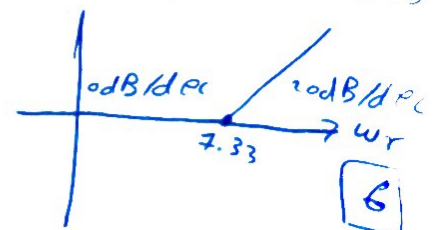
② $1/(1 + j\frac{\omega r}{0.38})$; $-\tan^{-1}(\frac{\omega r}{0.38})$



③ $(1 - j\omega r)$; $-\tan^{-1}(\omega r)$



④ $1 + \frac{j\omega r}{7.33}$; $\tan^{-1}(\frac{\omega r}{7.33})$



$$W_{gc} = 0.6$$

W_r	0	0.01	0.1	0.38	0.6	1	7.33	100
ϕ	-90	-92°	-109.67	-152.8	-173.94	-196.43	-209.47	-183.4

at $W_r = \infty \Rightarrow \phi = -180$

عند قيمته لا GM لها دوران سوا عنهم وهو الأصغر